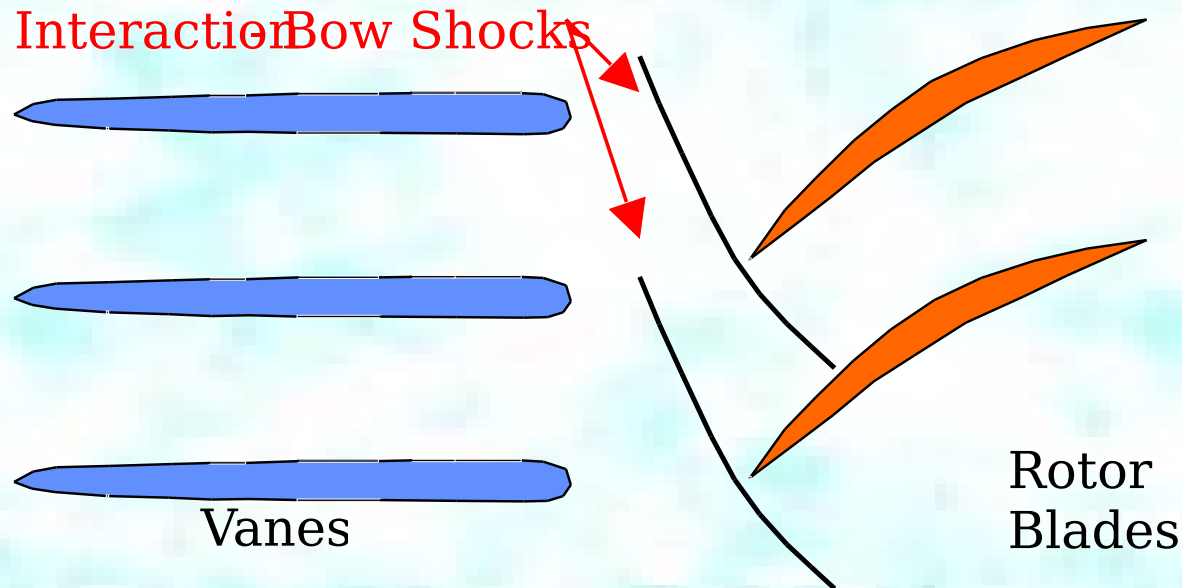


High Spatial Resolution MEMS Surface Pressure Sensor Array for Transonic Compressor IGV Measurement

Tim J. Leger, David A. Johnston, J. Mitch Wolff
Department of Mechanical & Materials Engineering
Wright State University
Dayton, Ohio

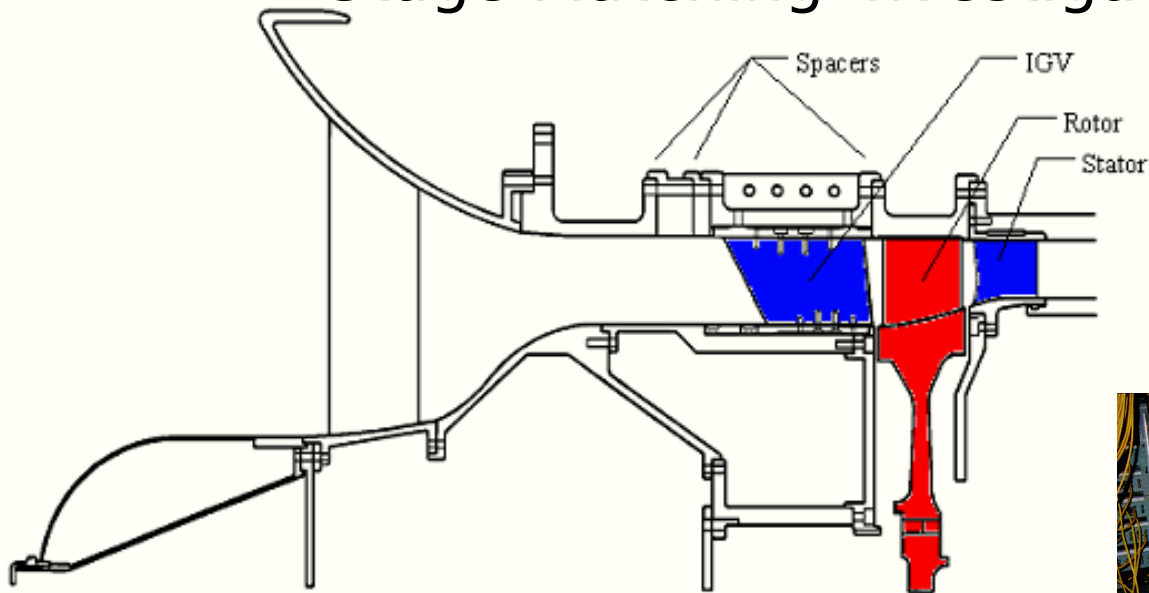
- Introduction
- IGV Instrumentation
 - Research Facility
 - Previous Instrumentation
 - Flex Circuit Substrate
 - Pressure Transducer Dies
 - Multiplexer Array
 - Trimmer Circuits & Static Calibration
- Preliminary Measurements
- Conclusions

- Forced response is an important component of HCF analysis
 - Vane/blade interaction a principal cause of unsteady aerodynamics
 - Detailed measurements required to determine flow physics
- Shock interaction is a main driver in unsteady aerodynamics
 - Insight into bow shock flow physics is needed
 - Shock/boundary layer interaction in end-wall region is unknown
- MEMS technology is utilized to understand flow physics
 - Increased economical measurement resolution required
 - Decreased installation expense due to MEMS flex circuit technology



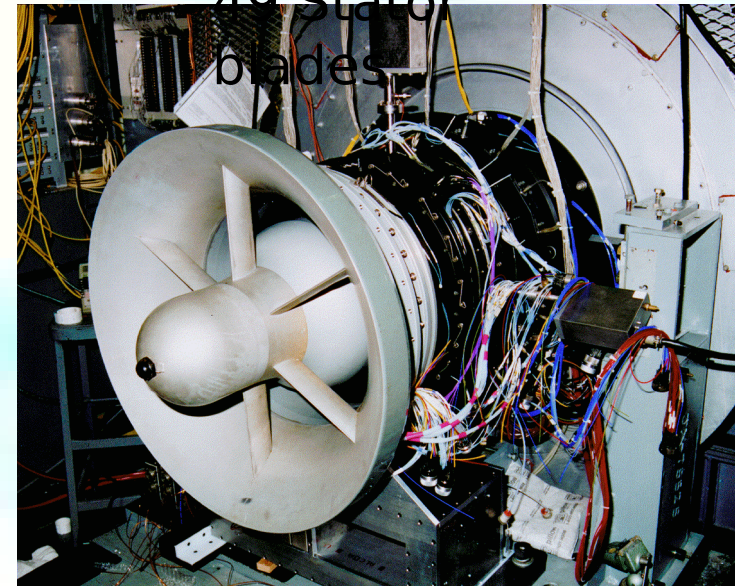
- Bow shocks are the primary unsteady driver
- High spatial & frequency resolution data is required to understand the complicated flow physics involved

Compressor Aero Research Laboratory (CARL) Stage Matching Investigation (SMI) Rig

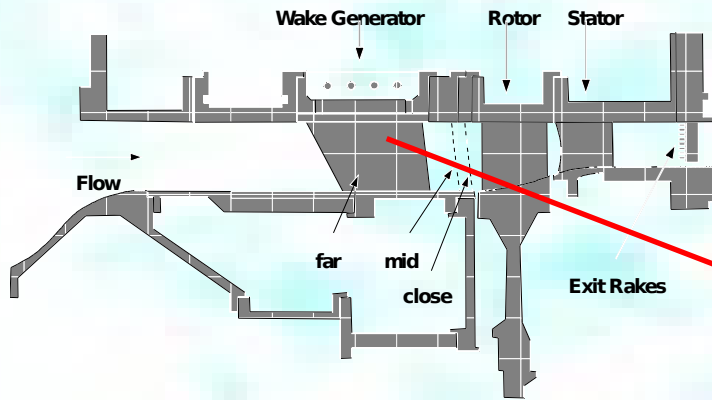


3 possible IGV/Rotor spacings:
12, 26, 56% IGV Chord
(0.36", 0.75", 1.68")

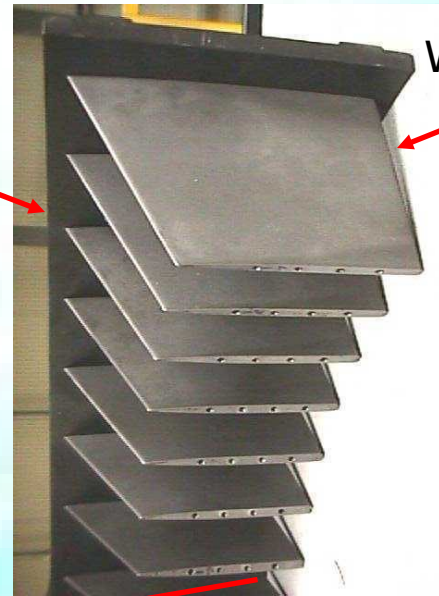
12, 24, 40
IGV's
33 Rotor
blades
49 Stator
blades



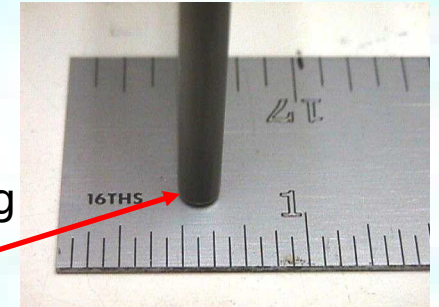
Inlet Guide Vane (IGV)



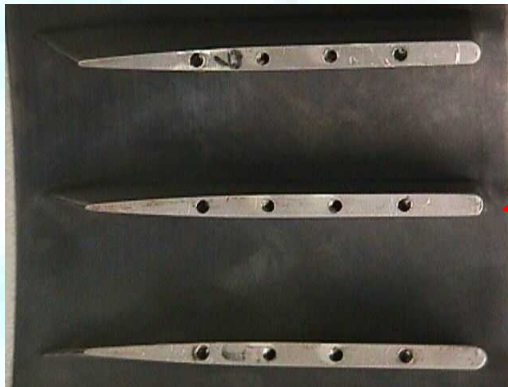
40-Strut Configuration



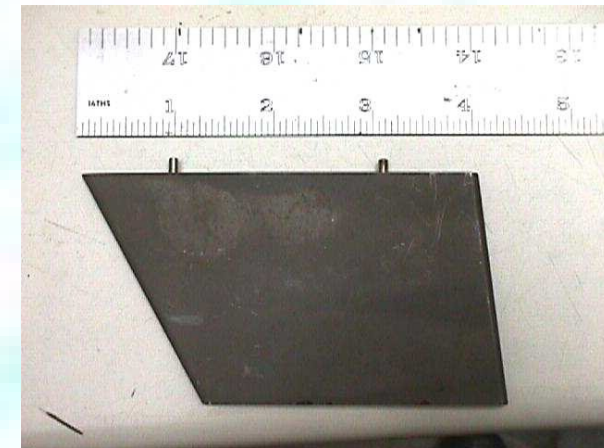
WG Trailing Edge



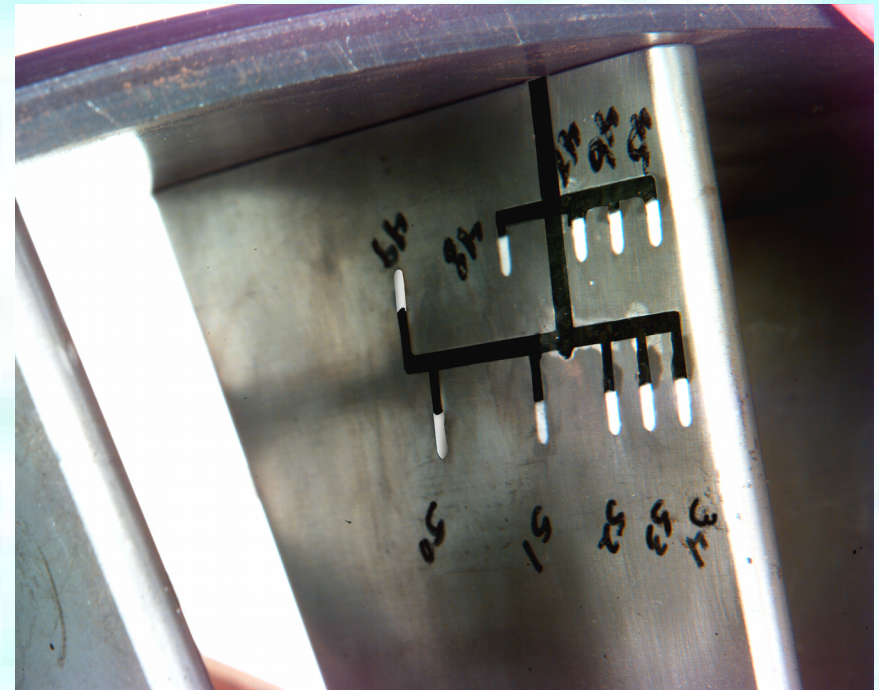
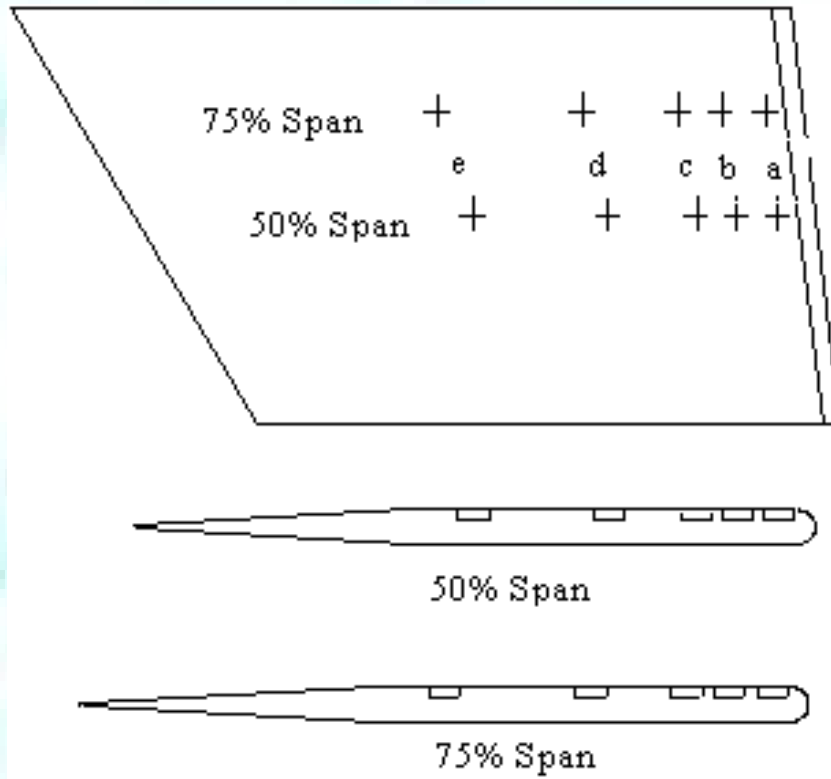
Trailing Edge Thickness
at Mid Chord
0.06



Airfoil Cross Section Hub



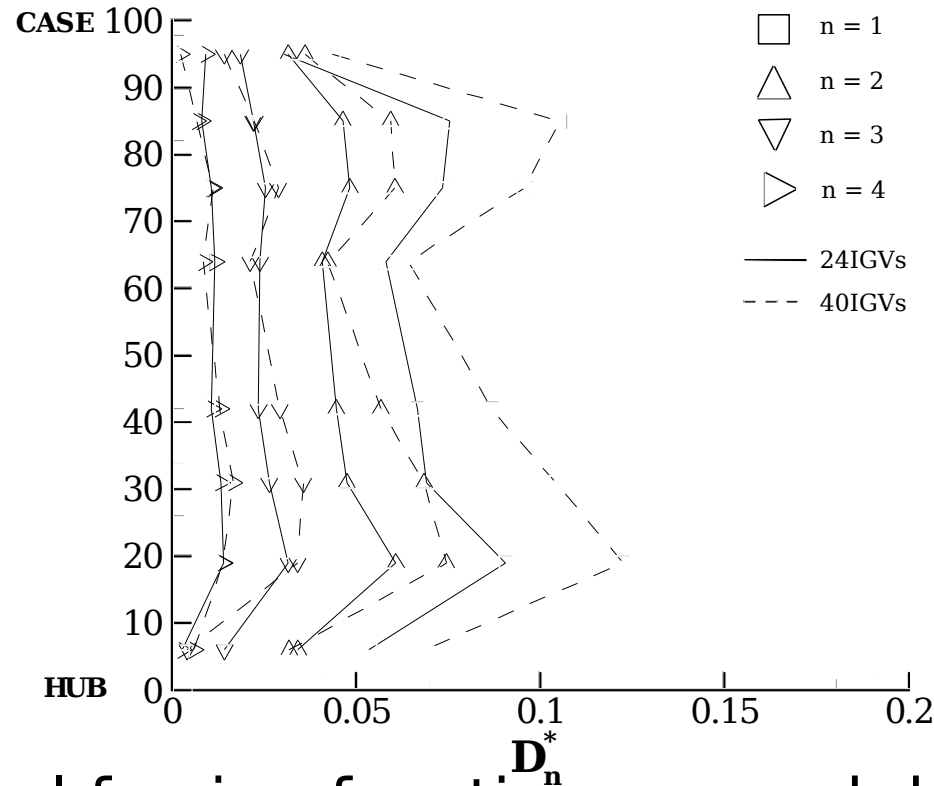
Previous Instrumentation



- 10 Kulite LQ-125 pressure transducers
- 25 psia
- 95%, 89%, 83%, 70%, 50% chordwise locations
- \$25,000

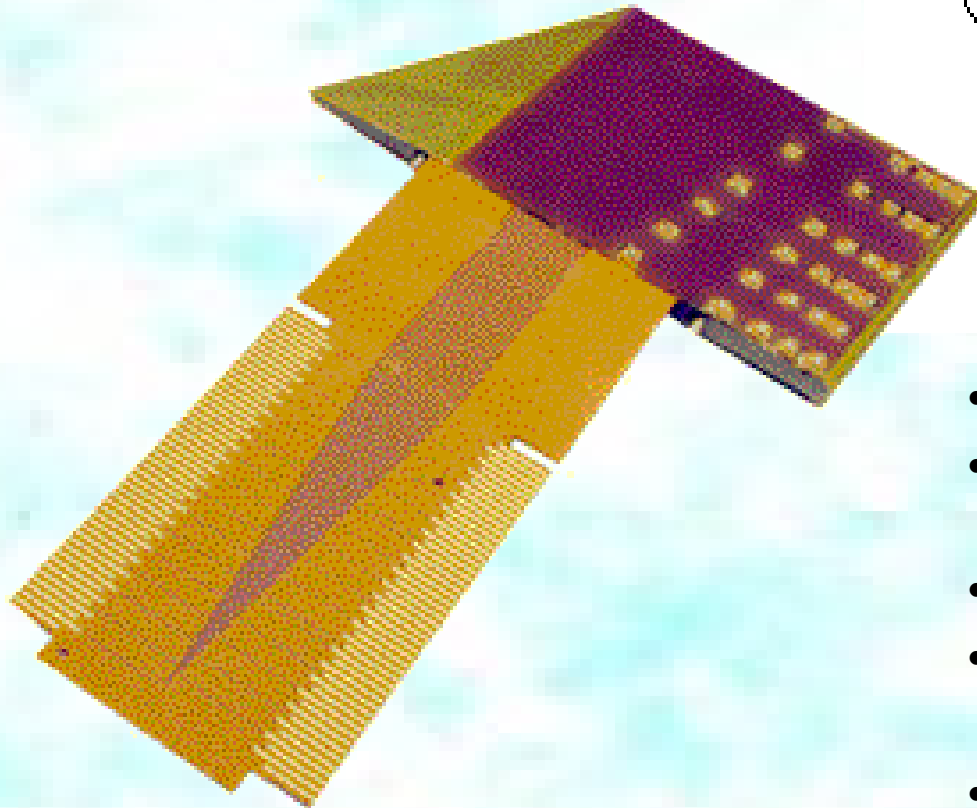
Probasco et al. 1997

3-D Flow Field



- Vortical forcing function research by Koch et al. 2000 demonstrates the 3-D nature of flow in the SMI rig

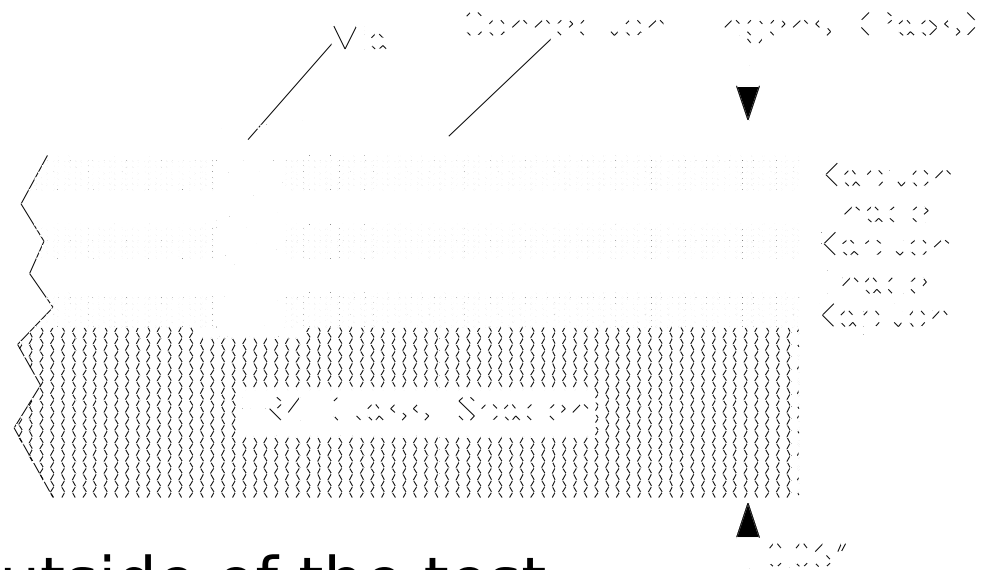
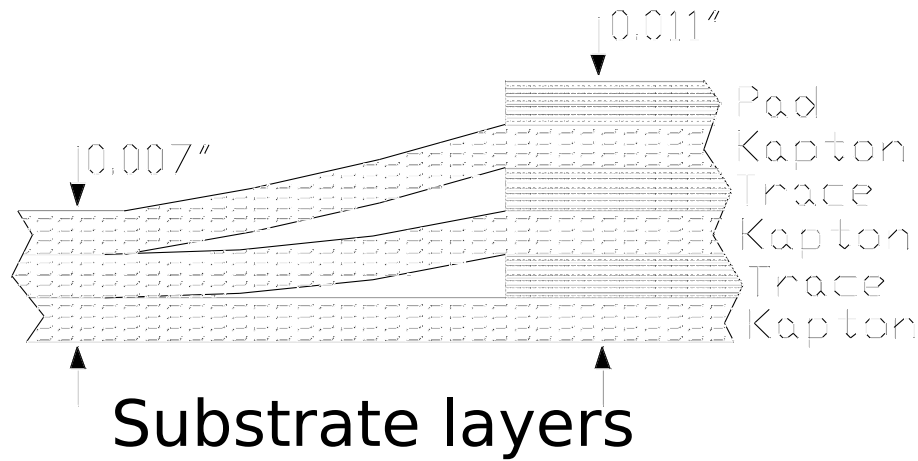
MEMS Sensor Array



95% Span	•	•	•	•	•
80% Span	•	•	•	•	•
65% Span	•	•	•	•	•
50% Span	•	•	•	•	•
25% Span	•	•	•	•	•
5% Span	•	•	•	•	•

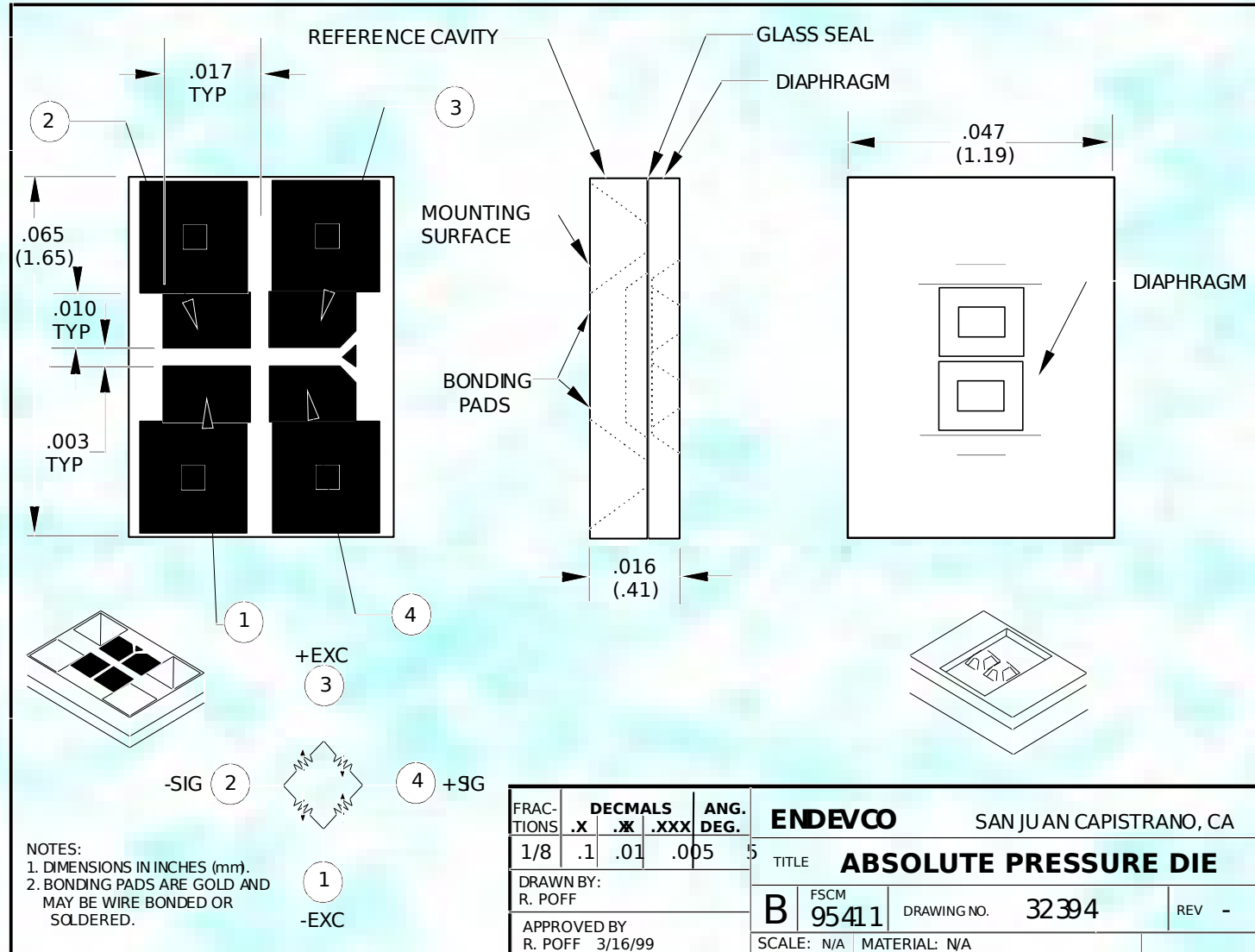
- 30 Sensors - 15 psia
- 3-layer flex circuit substrate ~ 0.01" thick
- ~ 0.03" total thickness
- 95%, 90%, 85%, 77%, 60% chordwise locations
- \$40,000

Flex Circuit Substrate

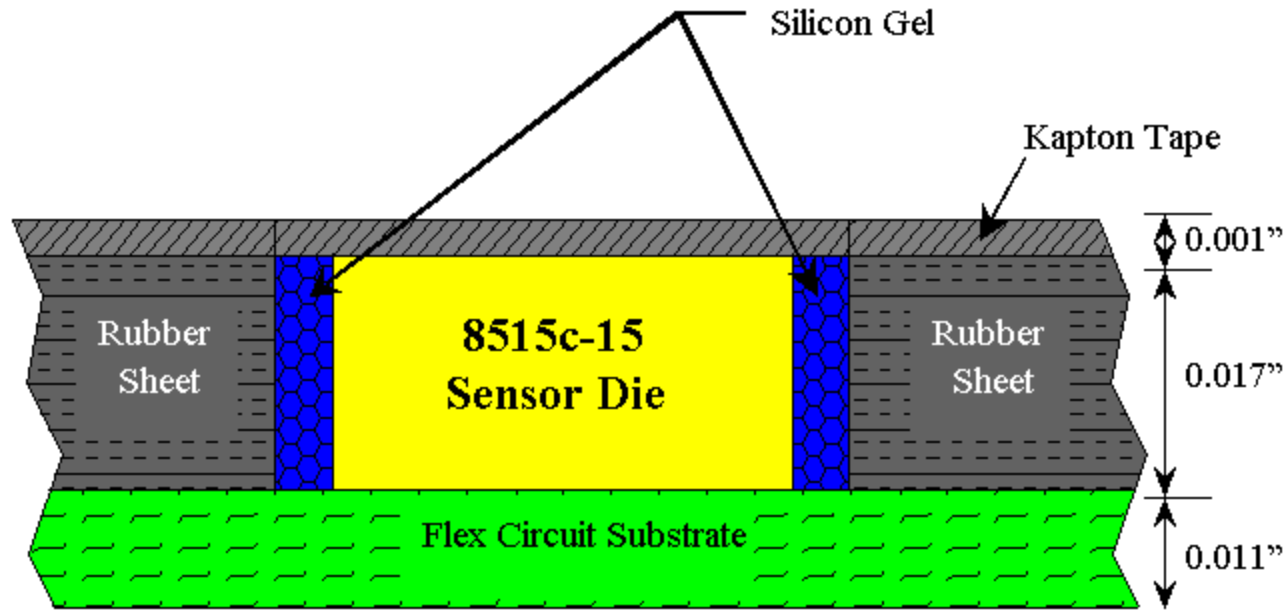


Outside of the test section

Pressure Transducer Dies

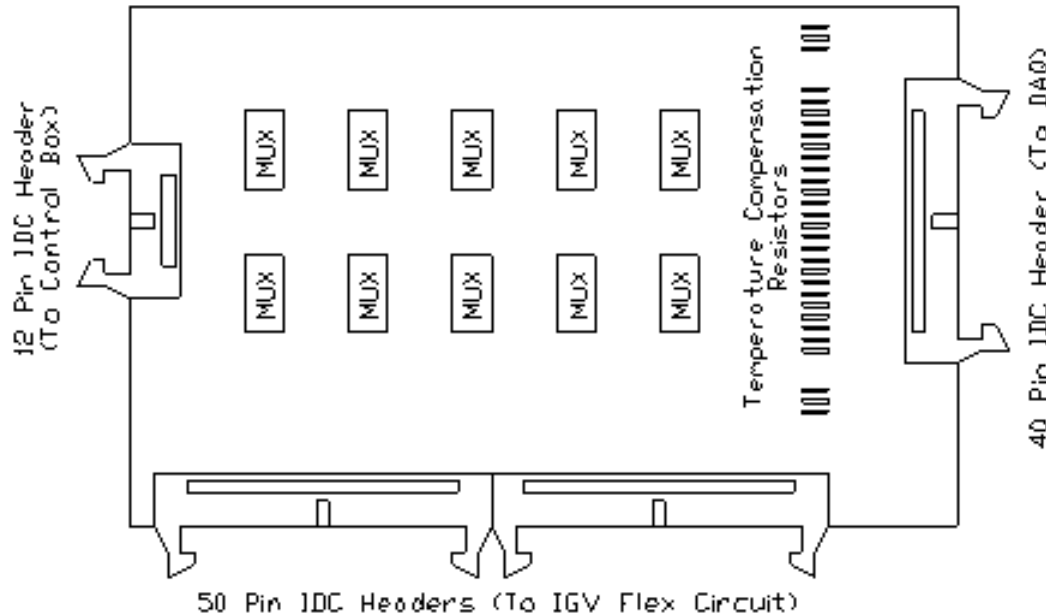


Sensor Application



- 30 mil slot machined in IGV
- Rubber sheet fills between sensor dies
- Silicon gel & kapton tape used to contour surface

Multiplexed Array

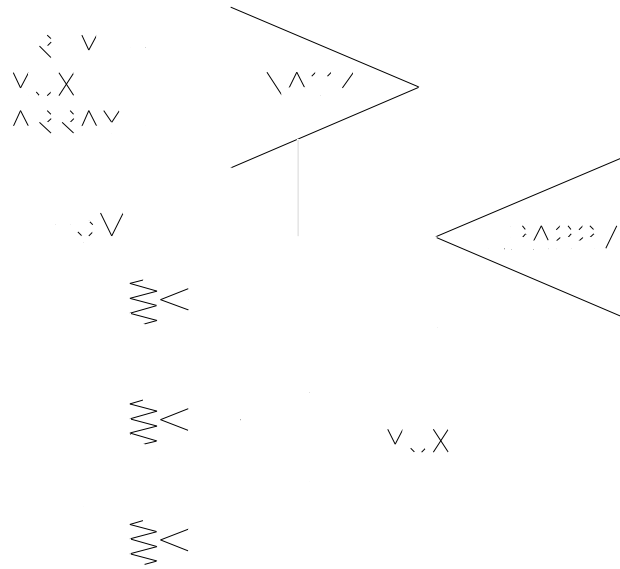


- 2-Board design (stackable)
- 10 MUX/board
- Incorporates thermal compensation resistors
- Remotely controllable

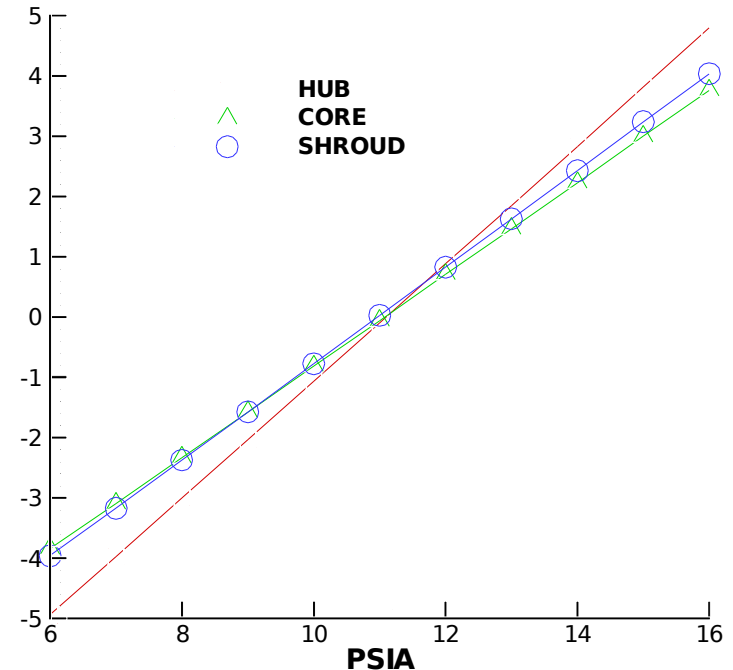


95% Span	□ □ □ □ □	Shroud Region A0=0, A1=1
80% Span	□ □ □ □ □	
65% Span	□ □ □ □ □	Core Region A0=1, A1=0
50% Span	□ □ □ □ □	
25% Span	□ □ □ □ □	Hub Region A0=1, A1=1
5% Span	□ □ □ □ □	

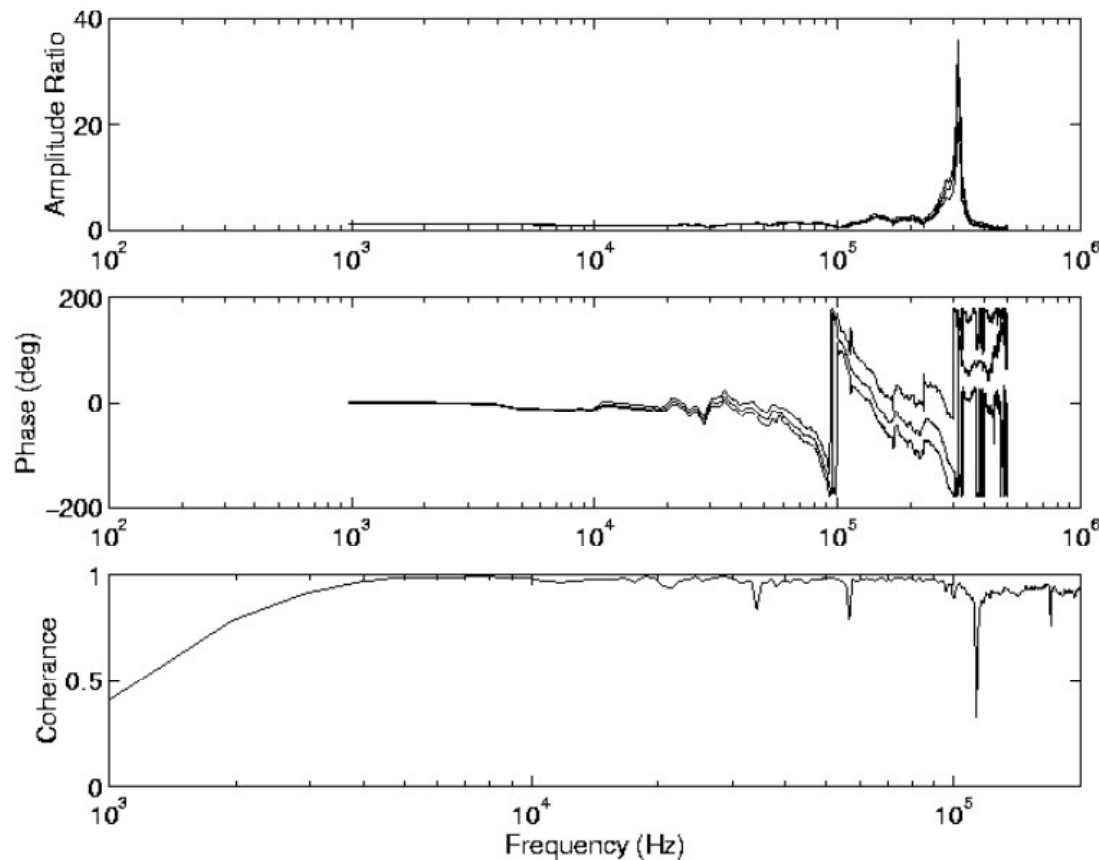
Trimmer Circuit &



DAQ Channel 1

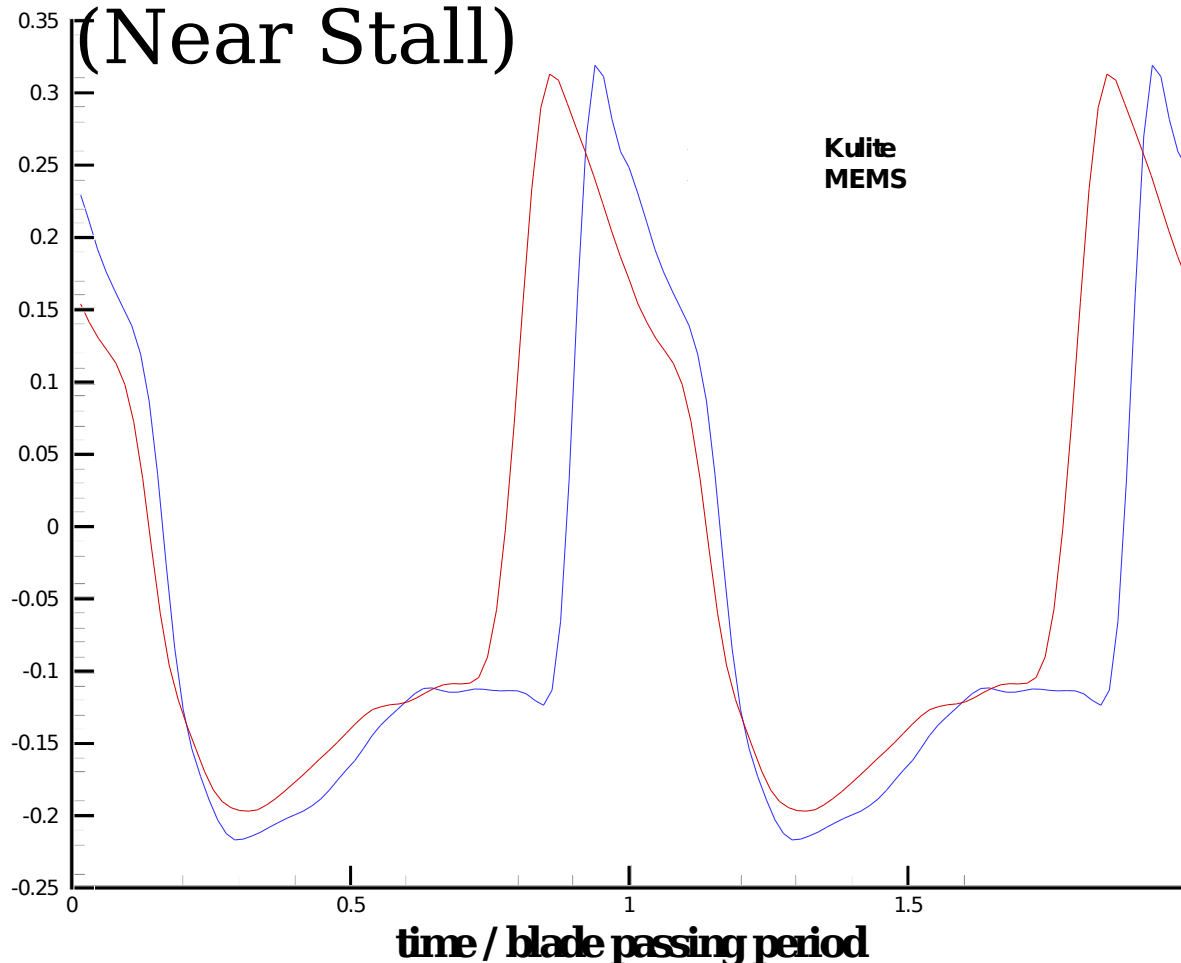


- Incorporation of the trimmer circuits allowed for a full DC signal to be obtained with the existing CARL DAQ system
- Static calibration showed excellent linearity of the MEMS pressure sensor array system



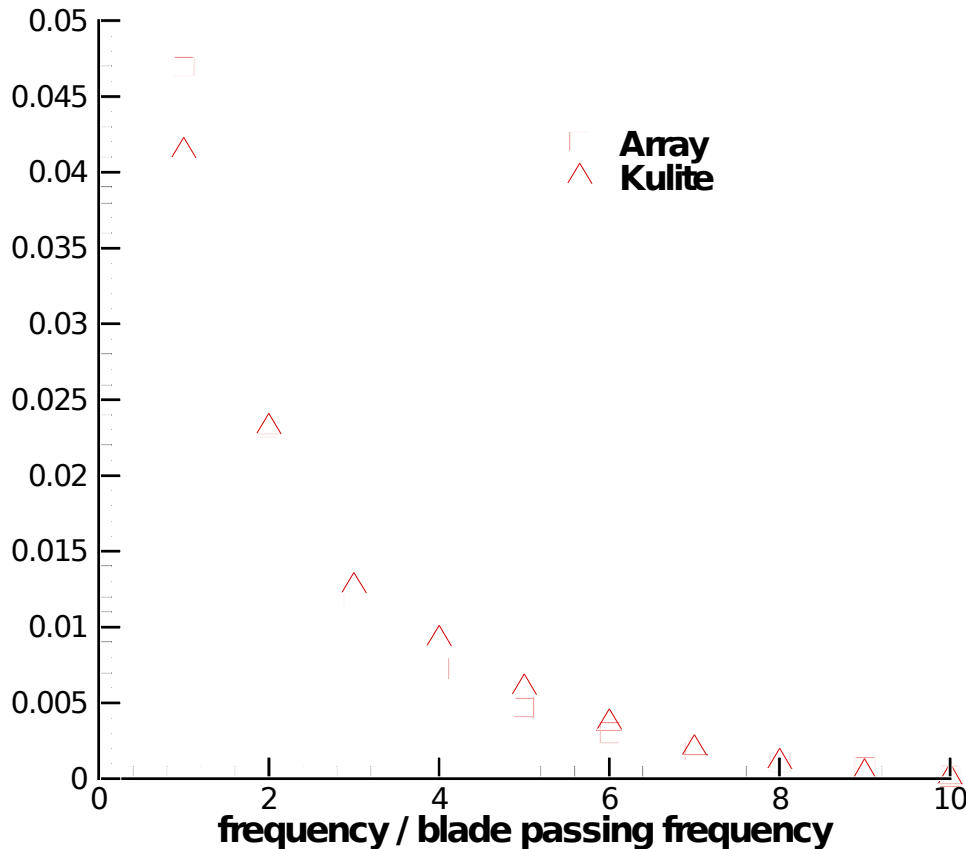
- WSU Shock Tube Testing
- Usable Frequency BW 30 kHz

50% Span, 95% Chord, 105% Speed
(Near Stall)



- Favorable agreement with previous sensor data
- Slight phase shift caused by annular shift in physical sensor location

Preliminary Measurements



- 50% Span, 90% Chord, 105% Speed
- 8% variation in 1st harmonic amplitude
- Differences caused by uncertainty in matching test conditions with different ambient conditions

- MEMS Sensors Designed and Installed
 - 2 IGV blades instrumented - 60 total sensors
 - High spatial and temporal resolution
 - AC and DC pressure components obtained
- High-speed transonic compressor unsteady aerodynamics data
 - Excellent agreement with previous traditional sensors
 - Tip region flow physics including shock/boundary layer interaction measured
 - Spacing and throttle position influences were measured